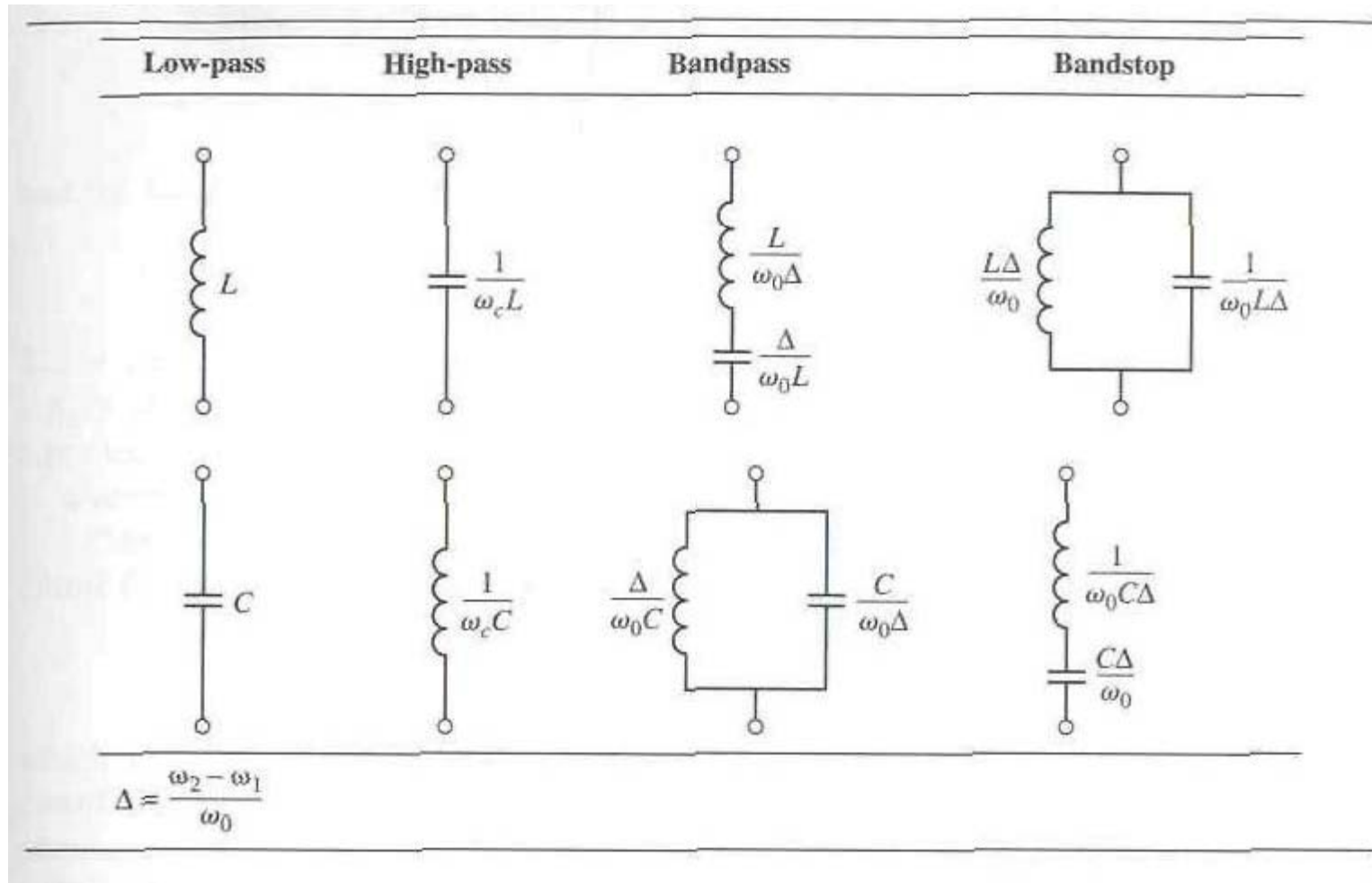
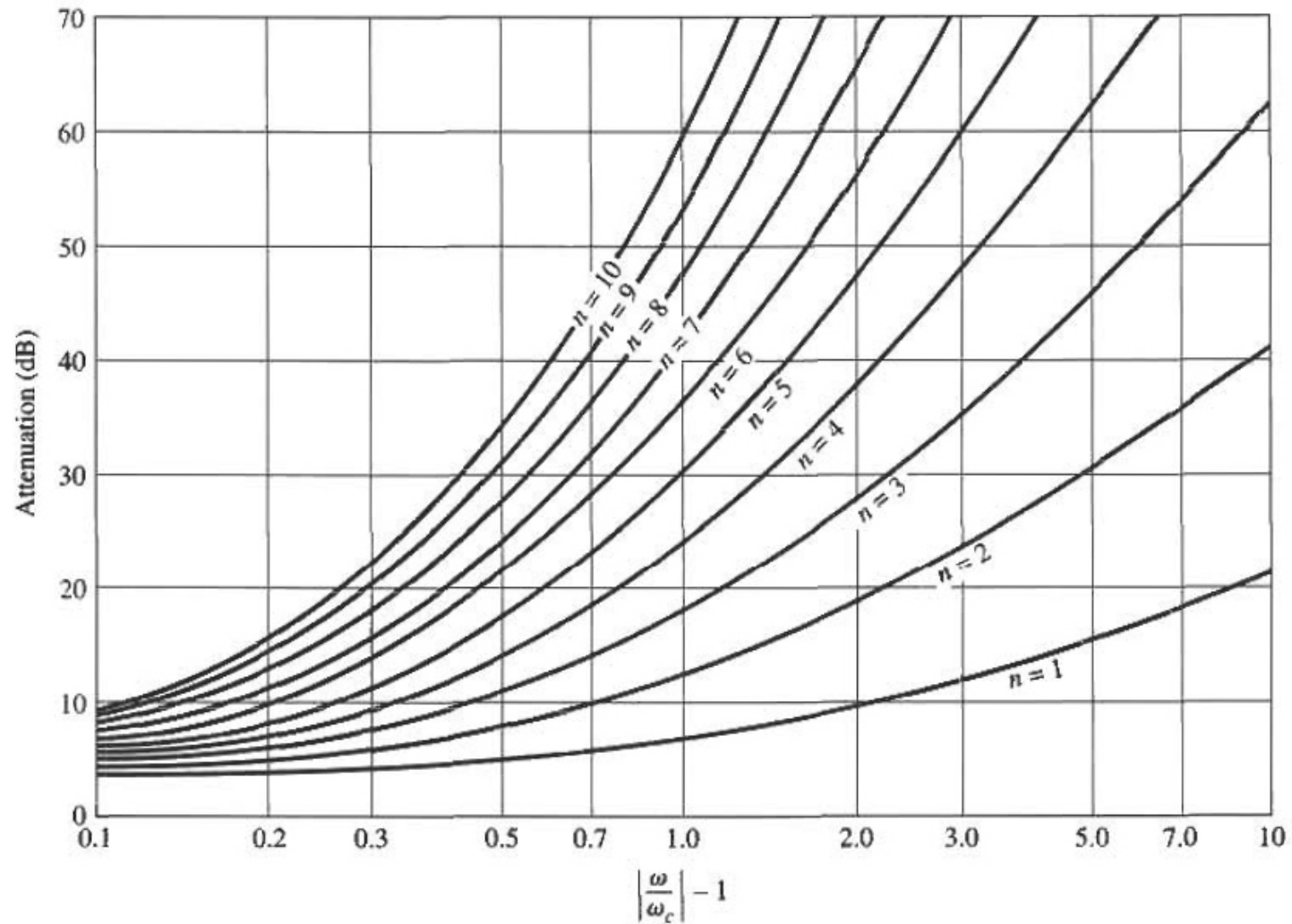


# FILTRE DE MICROUNDRE

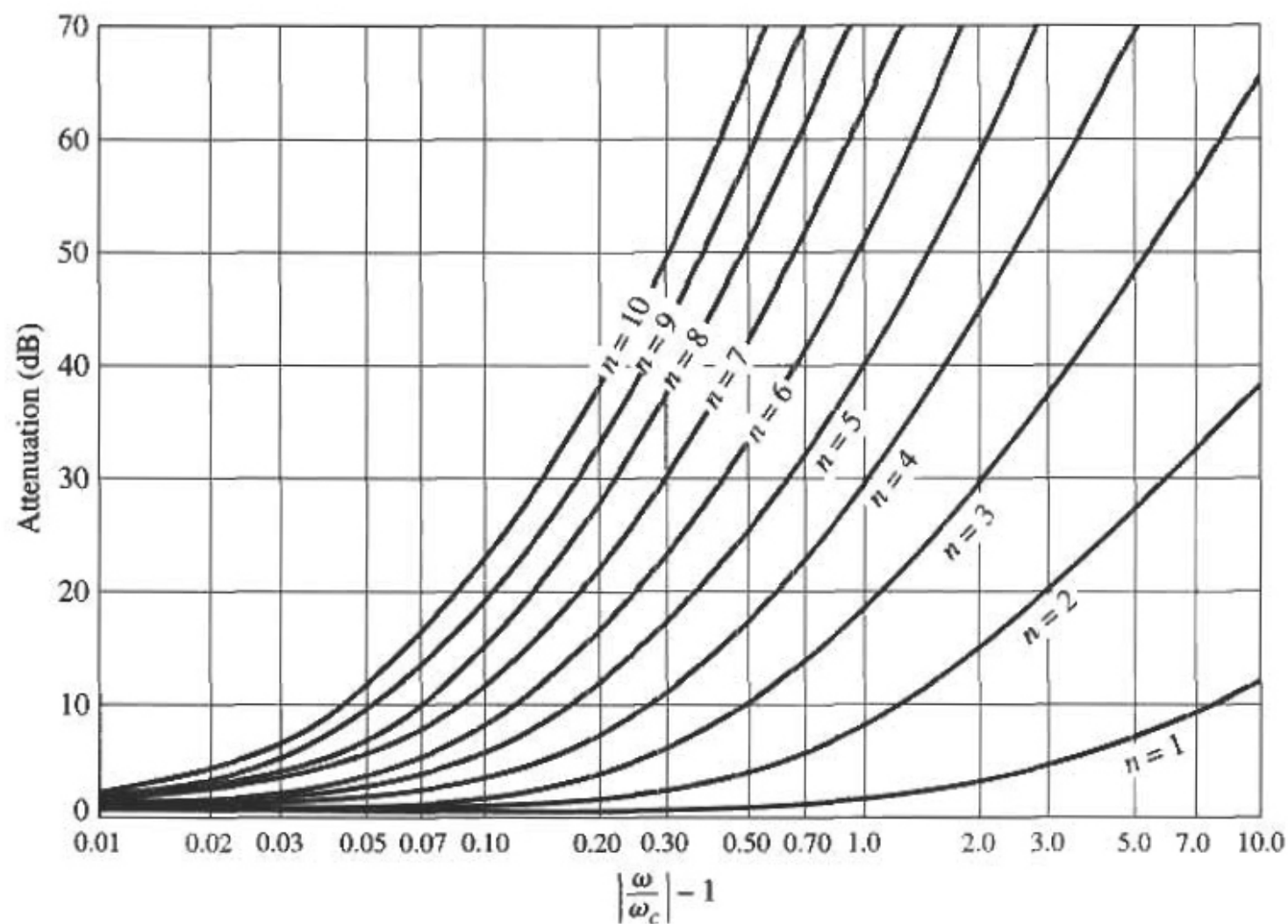
# Transformari ale filtrului prototip



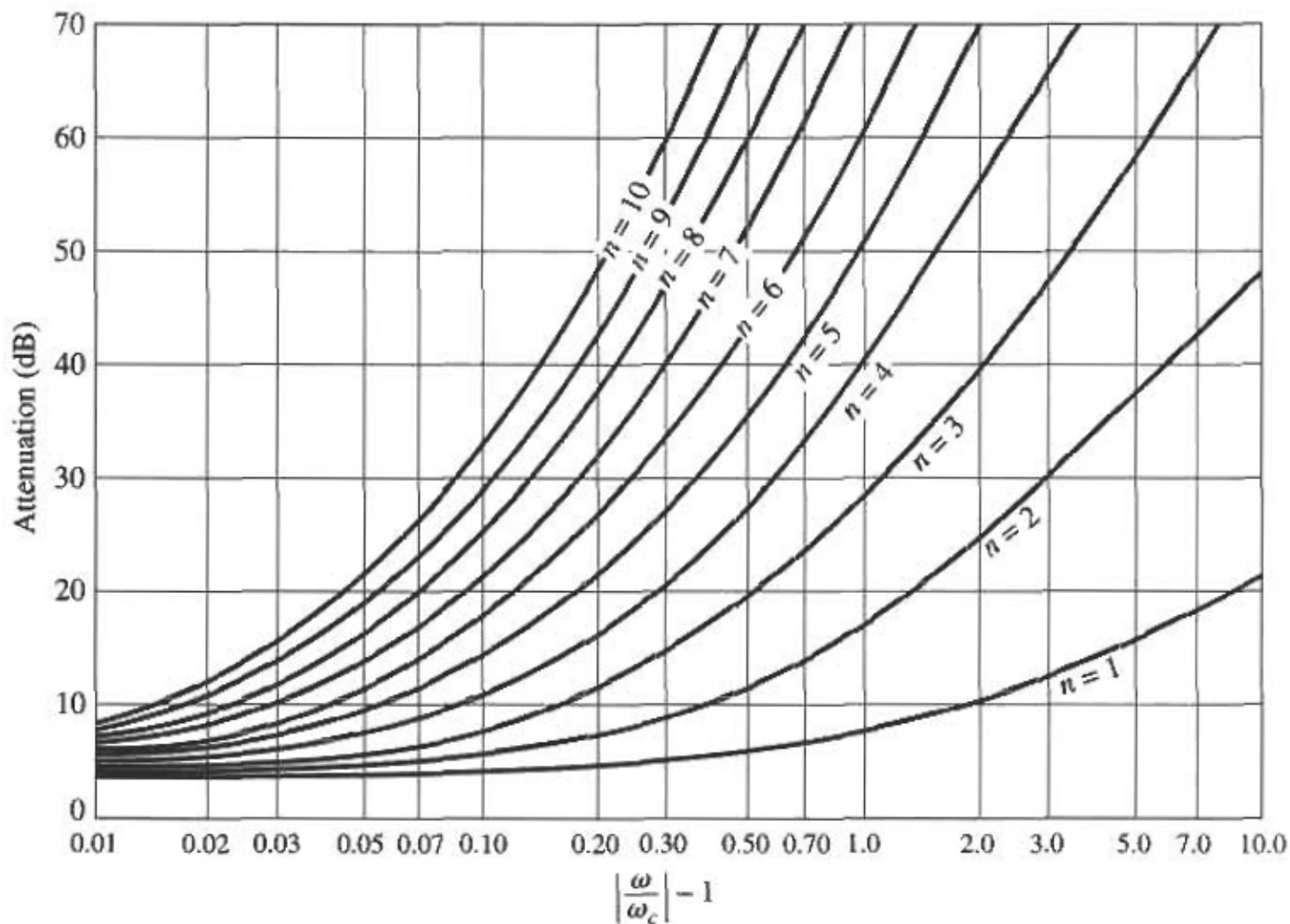
# Raspuns filtru prototip maxim plat



# Raspuns filtru prototip echiriplu 0.5 dB



# Raspuns filtru prototip echiriplu 3 dB



## **Implementarea filtrelor în domeniul microundelor**

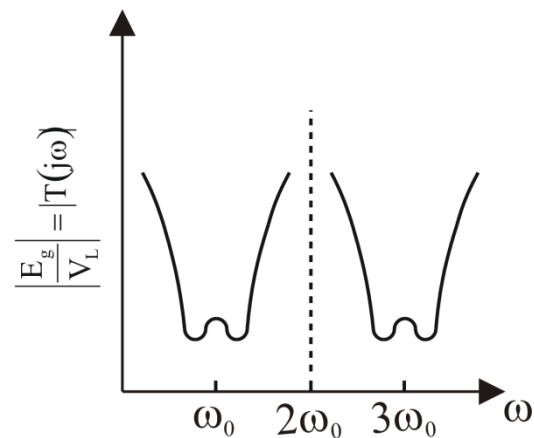
# Transformarea Richard

$$\Omega = \tan(\beta l) = \tan\left(\frac{\omega l}{v_p}\right)$$

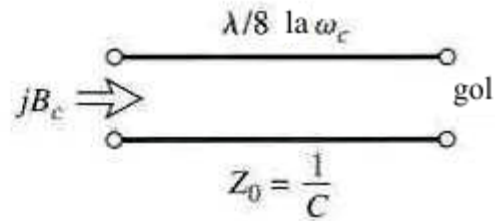
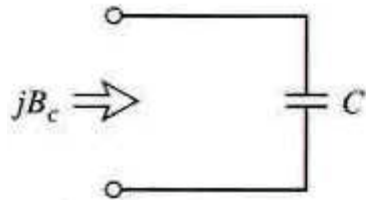
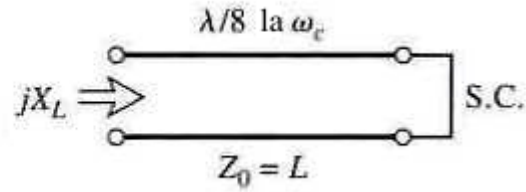
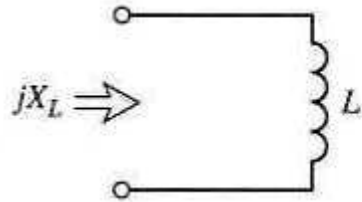
$$jX_L = j\Omega L = jL \tan(\beta l)$$

$$jB_C = j\Omega C = jC \tan(\beta l)$$

$\Omega = 1 = \tan(\beta l)$       pentru obtinerea aceleeeasi  
frecvente de taiere  $\omega_c$



# Transformarea Richard

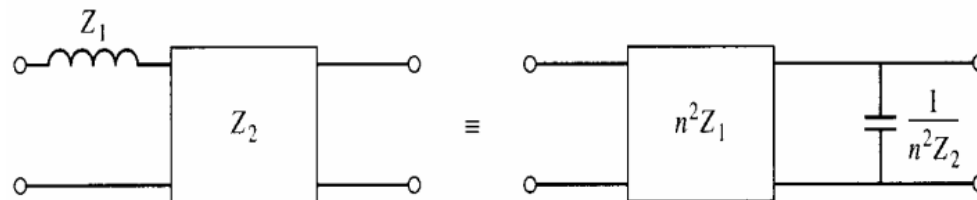
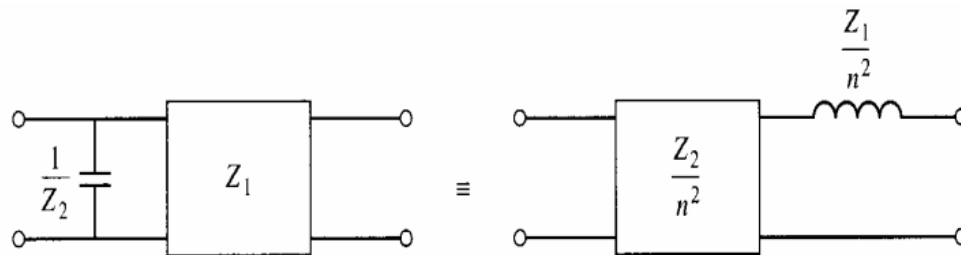


$$jX_L = j\Omega L = jL \tan(\beta l)$$

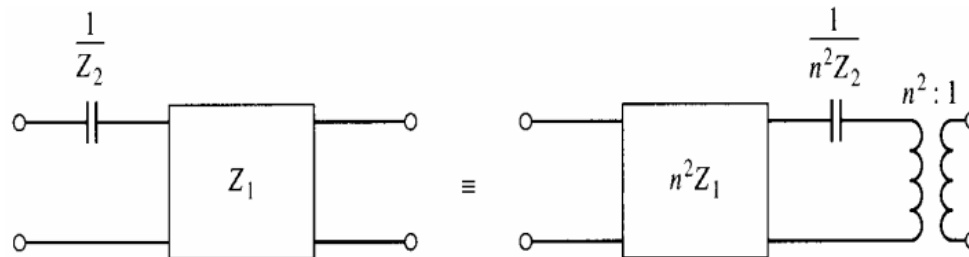
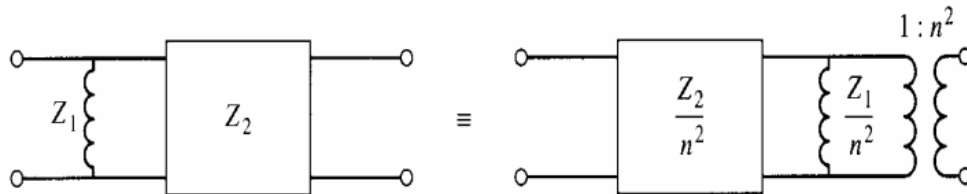
$$jB_C = j\Omega C = jC \tan(\beta l)$$



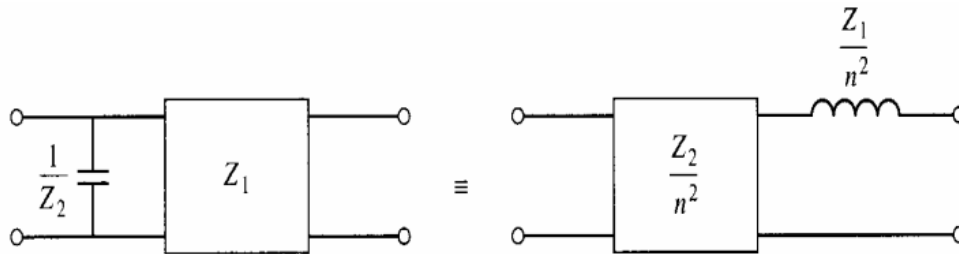
# Identitățile Kuroda $n^2 = 1 + Z_2/Z_1$



# Identitățile Kuroda $n^2 = 1 + Z_2/Z_1$



# Identitățile Kuroda $n^2 = 1 + Z_2/Z_1$



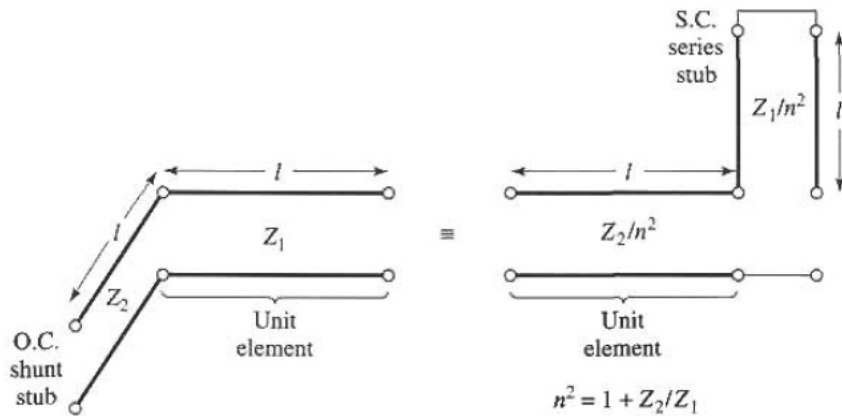
$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} \cos \beta \ell & j Z_1 \sin \beta \ell \\ \frac{j}{Z_1} \sin \beta \ell & \cos \beta \ell \end{bmatrix} = \frac{1}{\sqrt{1 + \Omega^2}} \begin{bmatrix} 1 & j \Omega Z_1 \\ \frac{j \Omega}{Z_1} & 1 \end{bmatrix}$$

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix}_L = \begin{bmatrix} 1 & 0 \\ \frac{j \Omega}{Z_2} & 1 \end{bmatrix} \begin{bmatrix} 1 & j \Omega Z_1 \\ \frac{j \Omega}{Z_1} & 1 \end{bmatrix} \frac{1}{\sqrt{1 + \Omega^2}}$$

$$= \frac{1}{\sqrt{1 + \Omega^2}} \begin{bmatrix} 1 & j \Omega Z_1 \\ j \Omega \left( \frac{1}{Z_1} + \frac{1}{Z_2} \right) & 1 - \Omega^2 \frac{Z_1}{Z_2} \end{bmatrix}$$

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix}_R = \begin{bmatrix} 1 & j \frac{\Omega Z_2}{n^2} \\ \frac{j \Omega n^2}{Z_2} & 1 \end{bmatrix} \begin{bmatrix} 1 & \frac{j \Omega Z_1}{n^2} \\ 0 & 1 \end{bmatrix} \frac{1}{\sqrt{1 + \Omega^2}}$$

$$= \frac{1}{\sqrt{1 + \Omega^2}} \begin{bmatrix} 1 & \frac{j \Omega}{n^2} (Z_1 + Z_2) \\ \frac{j \Omega n^2}{Z_2} & 1 - \Omega^2 \frac{Z_1}{Z_2} \end{bmatrix}$$



# Exemplu

Să se proiecteze un filtru trece-jos în tehnologie microstrip. Specificațiile sunt: frecvența de tăiere 4 GHz, ordinul 3, impedanța de 50  $\Omega$ , și o caracteristică echi-riplu de 3 dB.

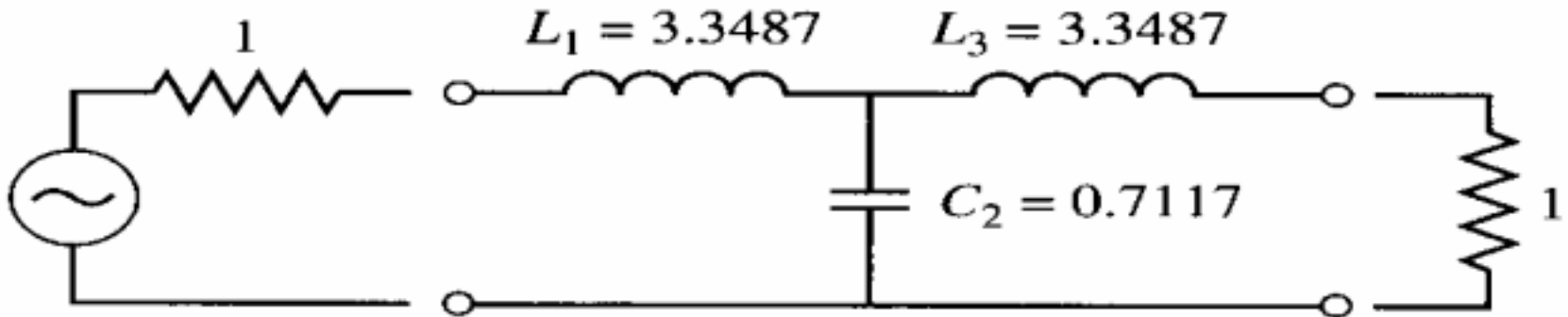
## Solutie

$$g_1 = 3.3487 = L_1$$

$$g_2 = 0.7117 = C_2$$

$$g_3 = 3.3487 = L_3$$

$$g_4 = 1.0000 = R_L$$

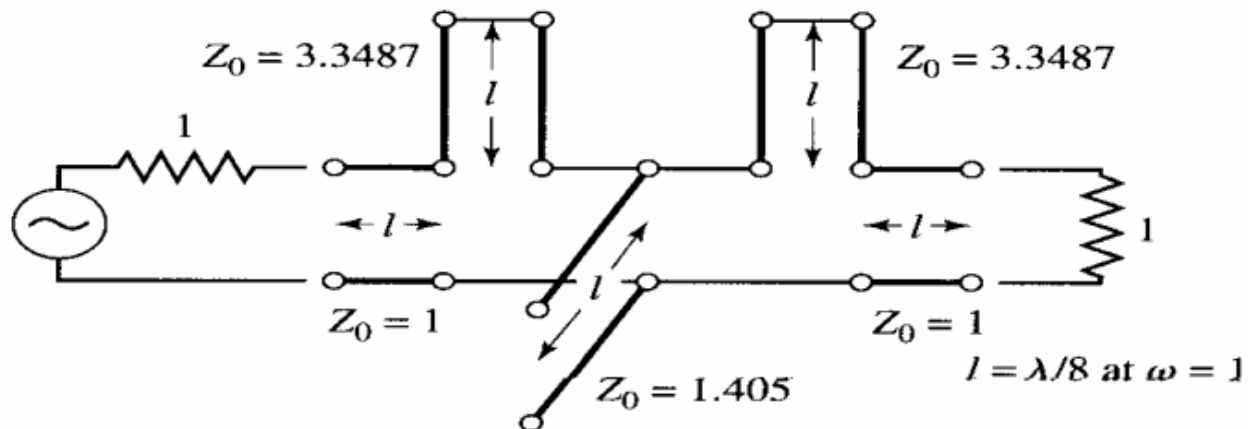
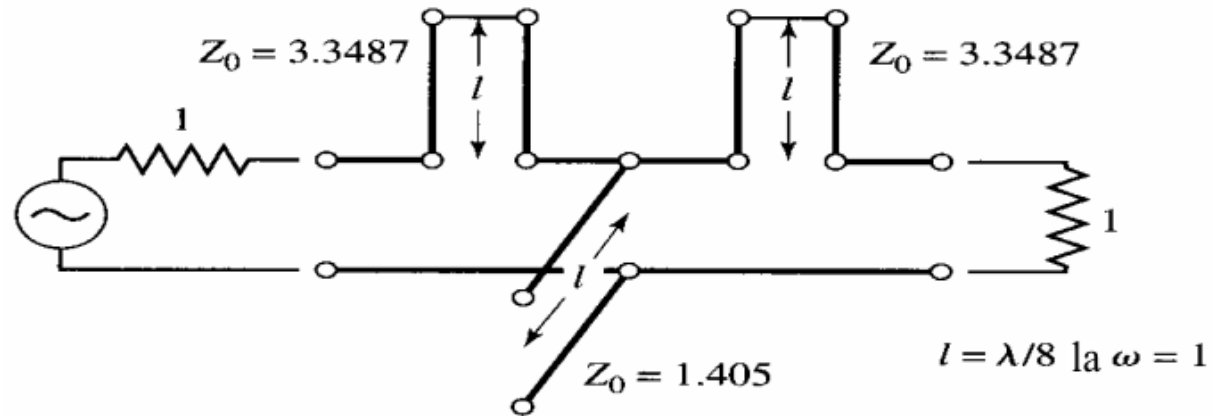


## Solutie - 2

$$Z_{L1} = L_1$$

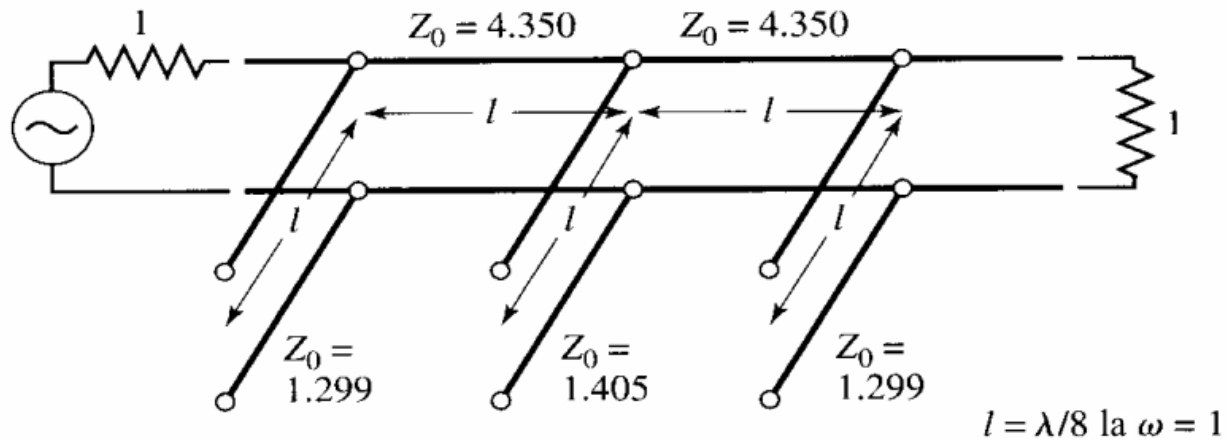
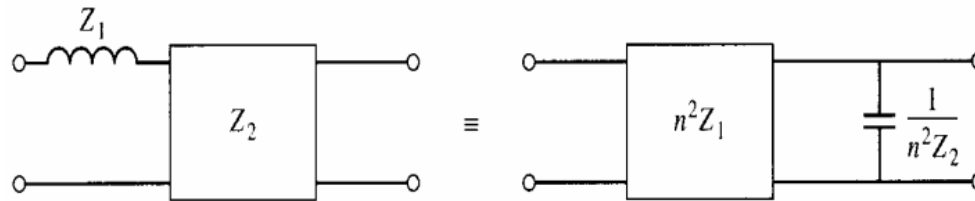
$$Z_{C2} = \frac{1}{C_2}$$

$$Z_{L3} = L_3$$



## Solutie - 3

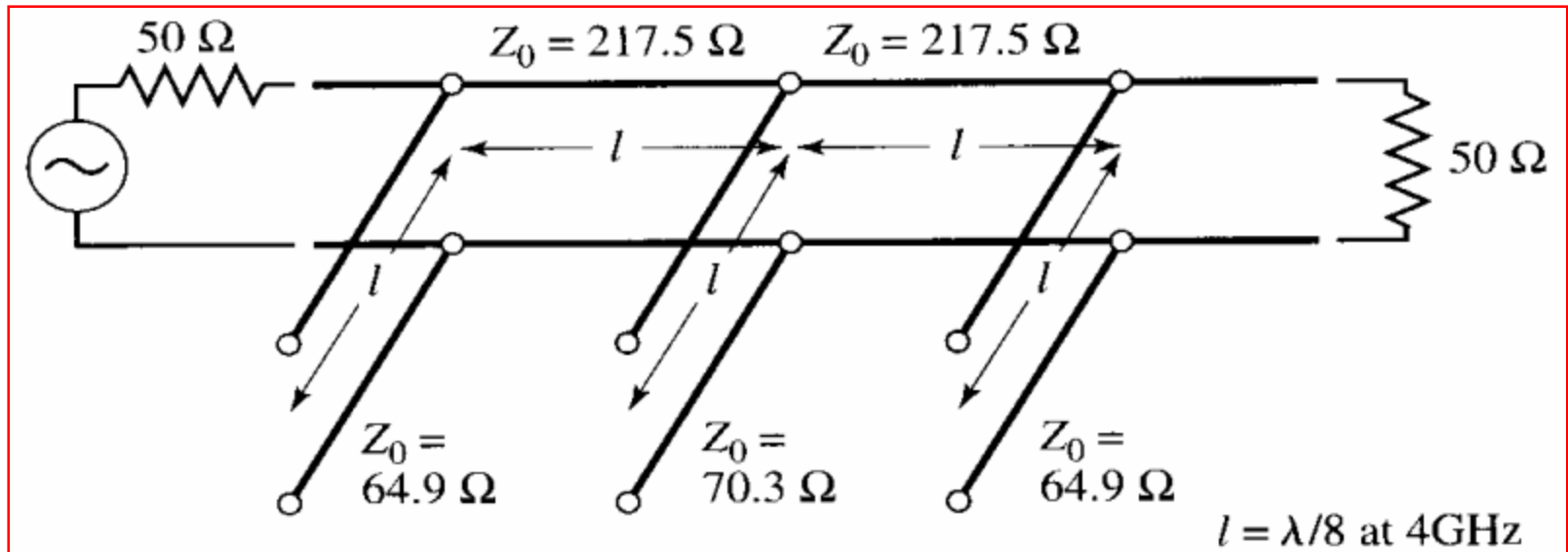
$$n = \sqrt{1 + \frac{R_L}{Z_{L1}}} \quad n^2 = 1.299$$



## Solutie - 4

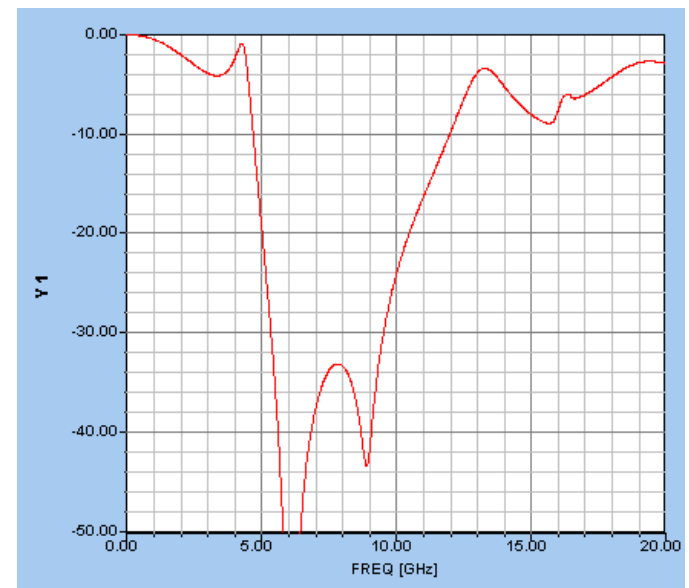
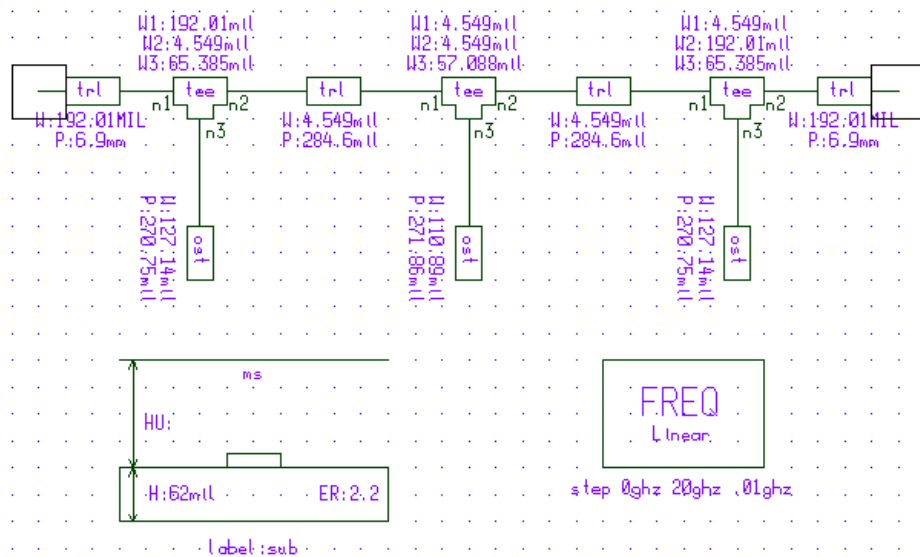
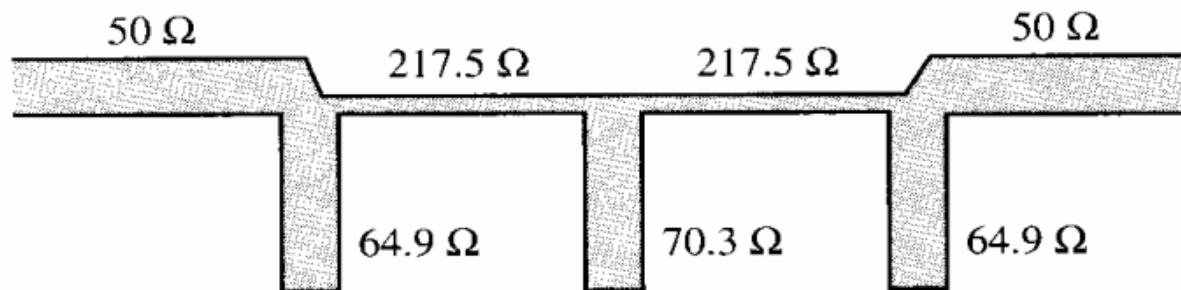
$$Z_{sh1} = n^2 Z_0 = 64.93\Omega \quad Z_{sh2} = Z_{C2} \cdot Z_0 = 70.254\Omega \quad Z_{sh3} = n^2 Z_0 = 64.93\Omega$$

$$Z_{se1} = n^2 \cdot Z_{L1} \cdot Z_0 = 217.435\Omega \quad Z_{se2} = n^2 \cdot Z_{L3} \cdot Z_0 = 217.435\Omega$$

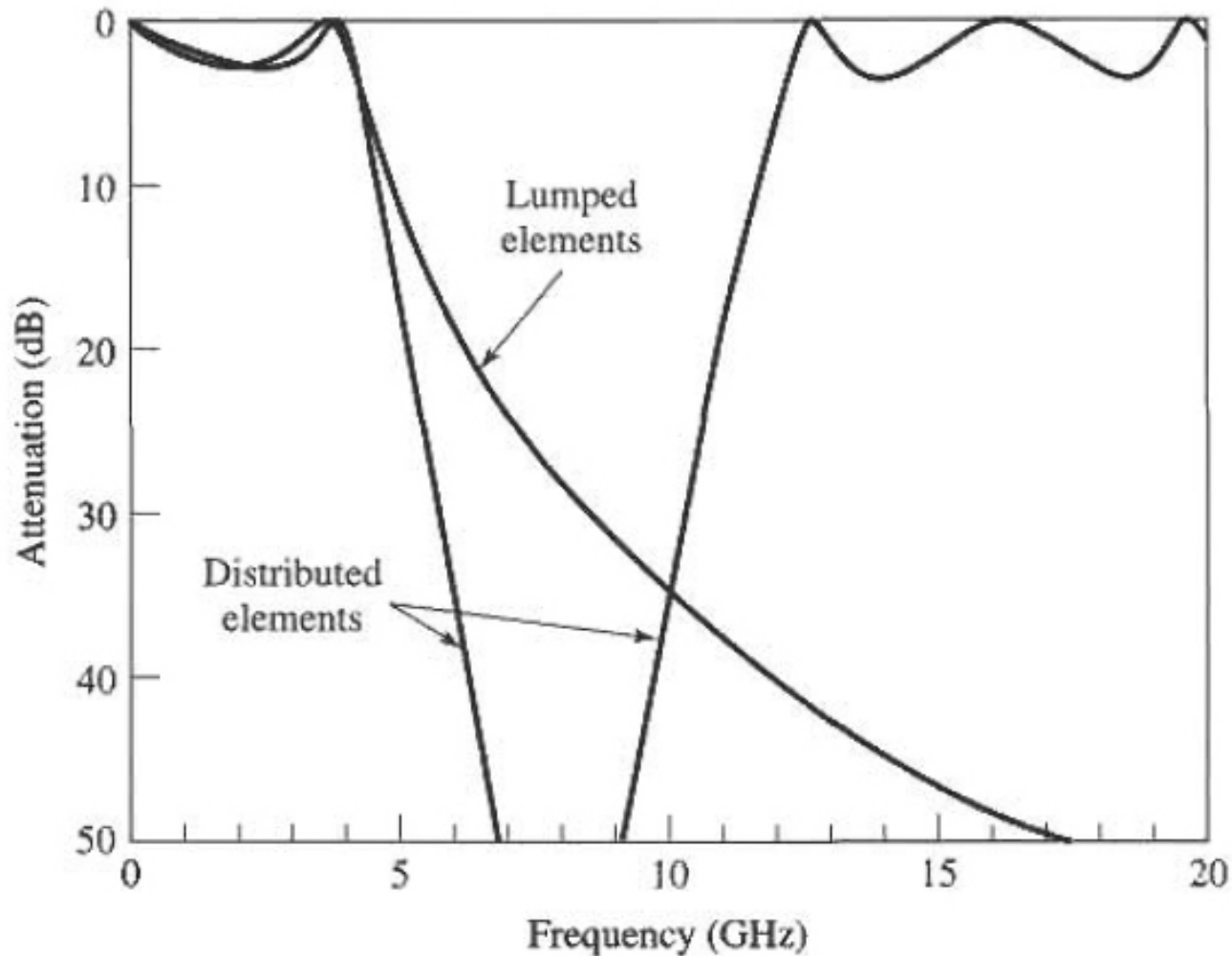




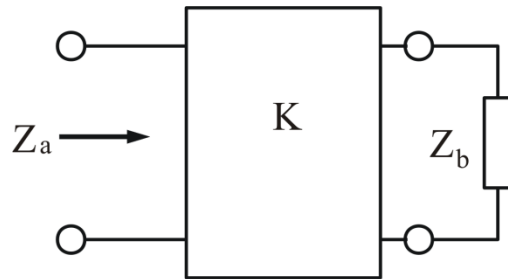
# Solutie – Filtrul realizat microstrip si simulat



# Comparatie elemente concentrate/distribuite

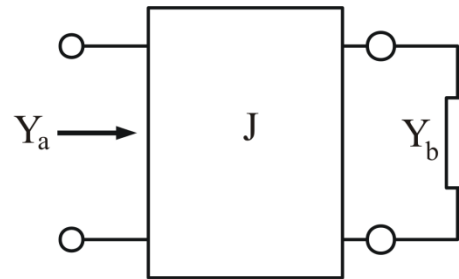


# Invertoare de admitanță și impedanță



Invertor de impedanta

(a)



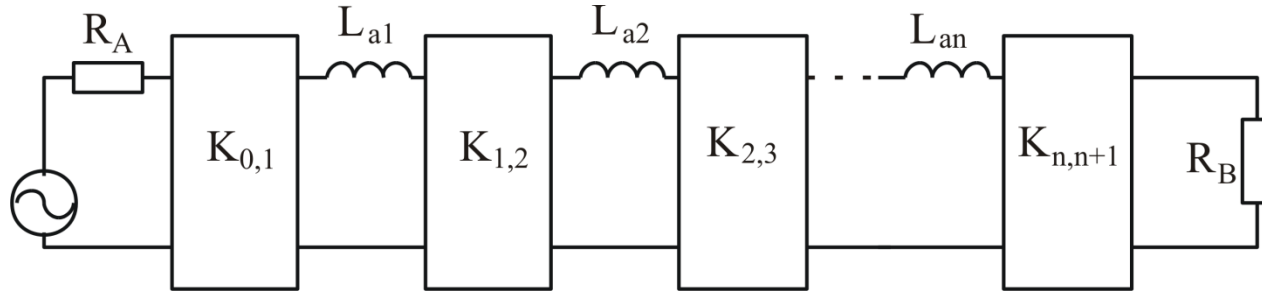
Invertor de admitanta

(b)

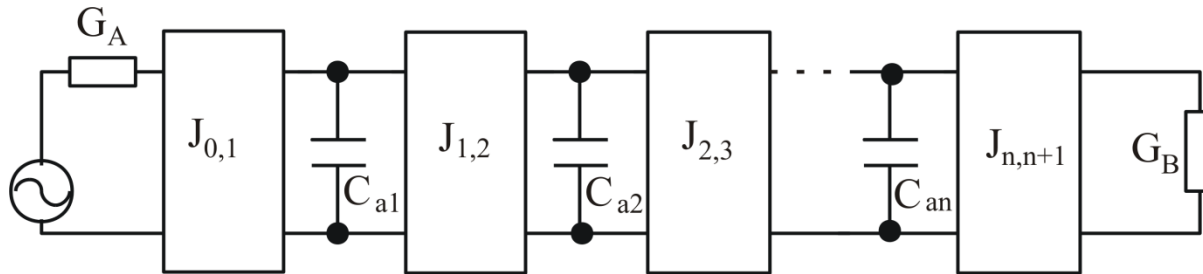
$$Z_a = \frac{K^2}{Z_b}$$

$$Y_a = \frac{J^2}{Y_b}$$

# Circuitele prototip modificate folosind invertoare

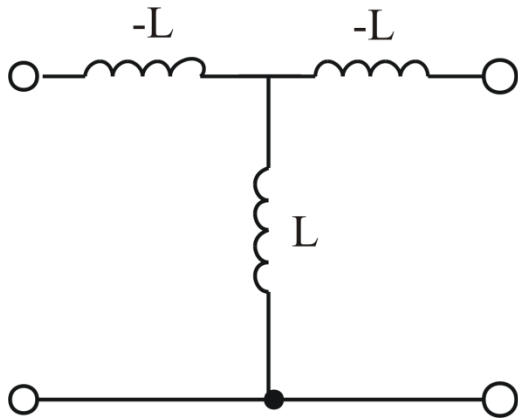


$$K_{01} = \sqrt{\frac{R_A L_{a1}}{g_0 g_1}}, K_{k,k+1} \Big|_{k=1, (n-1)} = \sqrt{\frac{L_{ak} L_{a(k+1)}}{g_k g_{k+1}}}, K_{n,n+1} = \sqrt{\frac{L_{an} R_B}{g_n g_{n+1}}}$$

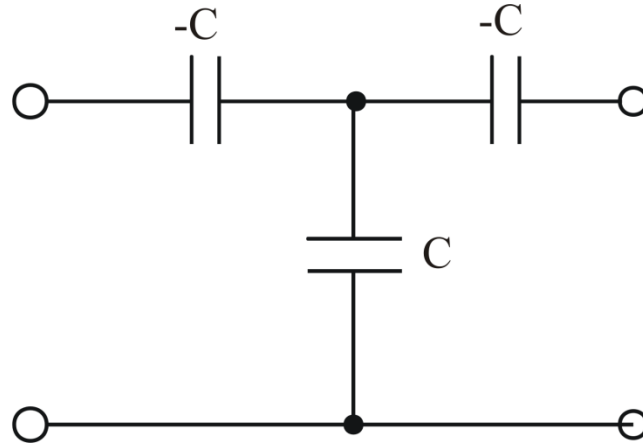


$$J_{01} = \sqrt{\frac{G_A C_{a1}}{g_0 g_1}}, J_{k,k+1} \Big|_{k=1, (n-1)} = \sqrt{\frac{C_{ak} C_{a(k+1)}}{g_k g_{k+1}}}, J_{n,n+1} = \sqrt{\frac{C_{an} g_B}{g_n g_{n+1}}}$$

# Realizări practice ale invertoarelor de impedanta- 1

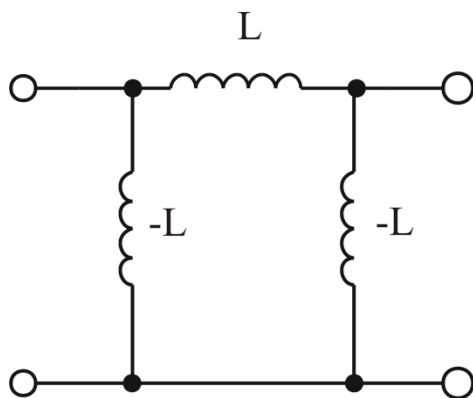


$$K = \omega L$$

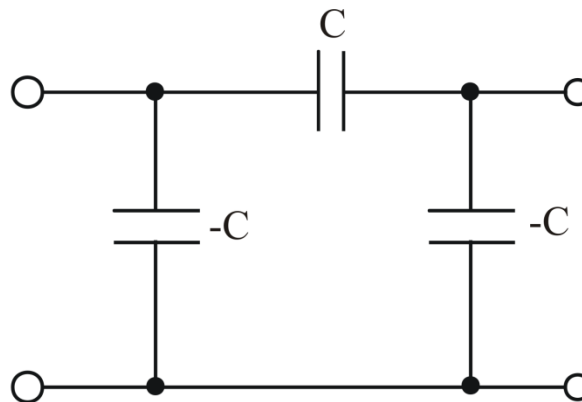


$$K = 1/\omega C$$

## Realizări practice ale invertoarelor de admitanta - 1

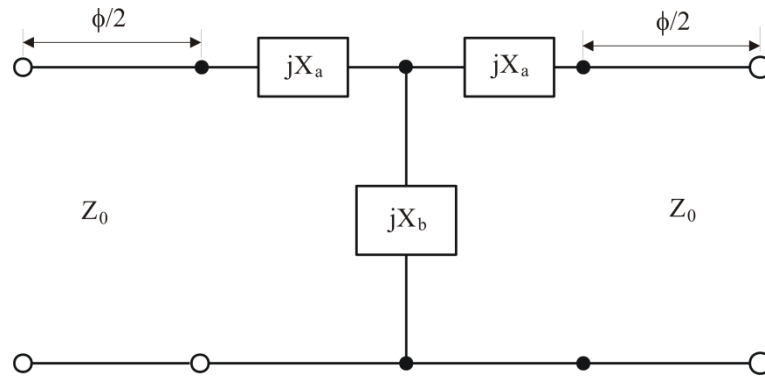


$$J = 1/\omega L$$

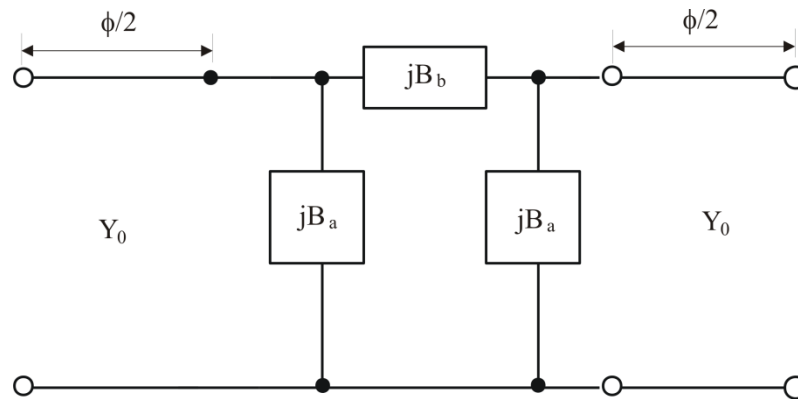


$$J = \omega C$$

# Realizări practice ale invertoarelor de imitanta- 2

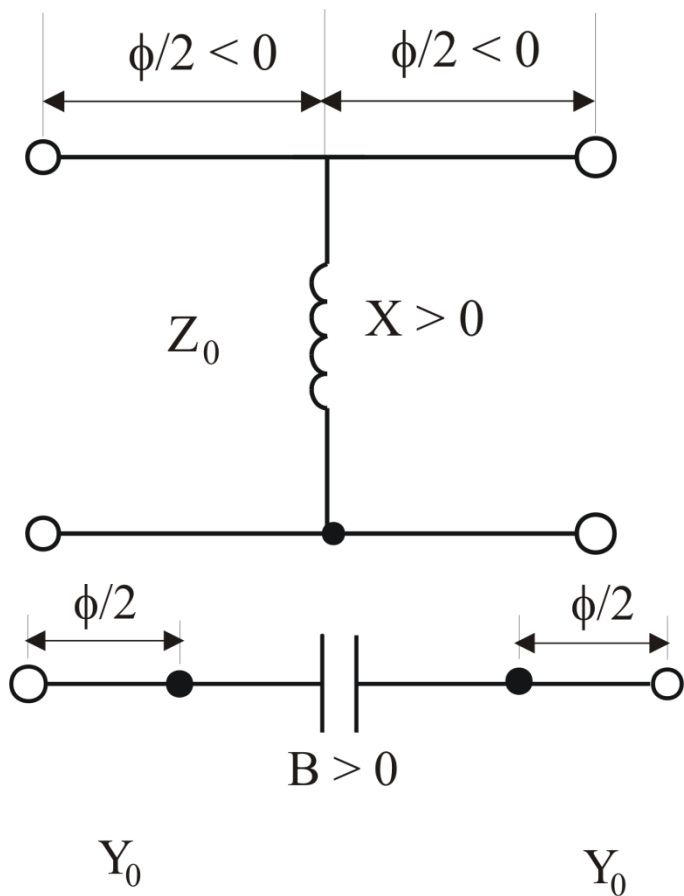


$$K = Z_0 \left| \operatorname{tg} \left( \frac{\phi}{2} + \operatorname{arctg} \frac{X_a}{Z_0} \right) \right| (\Omega), \phi = -\operatorname{arctg} \left( \frac{2X_b}{Z_0} + \frac{X_a}{Z_0} \right) - \operatorname{arctg} \frac{X_a}{Z_0} (\text{rad})$$



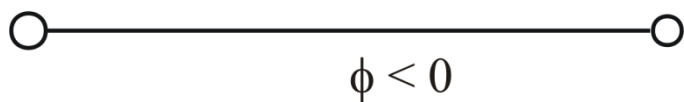
$$J = Y_0 \left| \operatorname{tg} \left( \frac{\phi}{2} + \operatorname{arctg} \frac{B_a}{Y_0} \right) \right| (\text{S}), \phi = -\operatorname{arctg} \left( \frac{2B_b}{Y_0} + \frac{B_a}{Y_0} \right) - \operatorname{arctg} \frac{B_a}{Y_0} (\text{rad})$$

# Realizări practice ale invertoarelor de imitanță - 3



$$K = Z_0 \operatorname{tg} \left| \frac{\phi}{2} \right| (\Omega), \quad \phi = -\operatorname{arctg} \left( \frac{2X}{Z_0} \right) (\text{rad}), \quad \left| \frac{X}{Z_0} \right| = \frac{K/Z_0}{1 - (K/Z_0)^2}$$

$$J = Y_0 \operatorname{tg} \left| \frac{\phi}{2} \right| (S), \quad \phi = -\operatorname{arctg} \left( \frac{2B}{Y_0} \right) (\text{rad}), \quad \left| \frac{B}{Y_0} \right| = \frac{J/Y_0}{1 - (J/Y_0)^2}$$

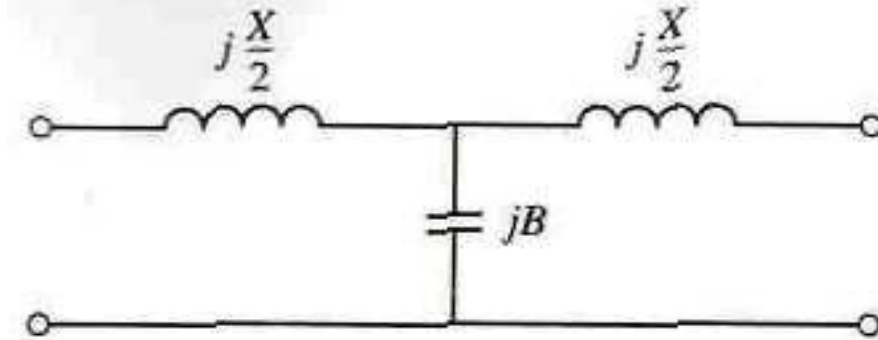




# Circuit echivalent pentru sectiuni scurte de linii

$$[Z] = \begin{bmatrix} -jZ_0 \cot(\beta l) & -jZ_0 \csc(\beta l) \\ -jZ_0 \csc(\beta l) & -jZ_0 \cot(\beta l) \end{bmatrix}$$

$$Z_{11} - Z_{12} = -jZ_0 \left[ \frac{\cos(\beta l) - 1}{\sin(\beta l)} \right] = jZ_0 \tan\left(\frac{\beta l}{2}\right)$$



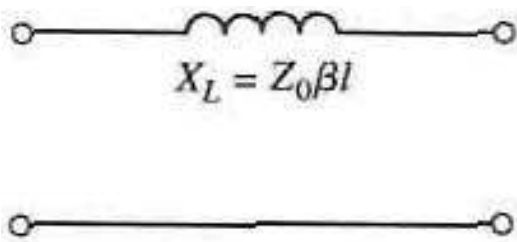
$$\beta l < \pi/2$$

$$\frac{X}{2} = Z_0 \tan\left(\frac{\beta l}{2}\right)$$

$$B = \frac{1}{Z_0} \sin(\beta l)$$

## Filtre trece-jos cu variații treaptă ale impedanței caracteristice

*Circuite aproximativ echivalente pentru secțiuni scurte de linie*

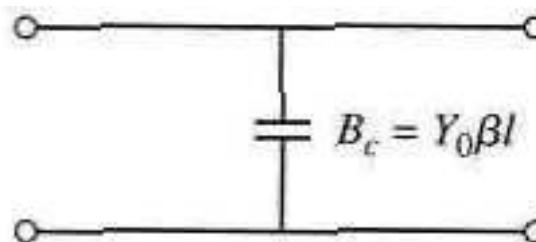


$$X \cong Z_0 \beta l$$

$$\beta l < \pi/4$$

$$Z_0 = Z_h$$

$$\beta l = \frac{LR_0}{Z_h} \quad (\text{bobină})$$



$$B \cong Y_0 \beta l$$

$$\beta l < \pi/4$$

$$Z_0 = Z_l$$

$$\beta l = \frac{CZ_l}{R_0} \quad (\text{condensator})$$

# Exemplu

Să se proiecteze un filtru trece-jos avînd un răspuns maxim-plat, frecvența de tăiere 2.5 GHz. Este necesar să avem mai mult de 20 dB pierderi de inserție la 4 GHz. Impedanța filtrului este  $50\Omega$ , cea mai mare impedanță caracteristică realizabilă practic este  $150\Omega$ , iar cea mai mică  $10\Omega$ .

## Solutia - 1

$$L_{As} = 20dB \quad L_{Ar} = 3dB \quad \omega'_S / \omega'_1 = 4.0/2.5 = 1.6$$

$$N = 6$$

$$g_1 = 0.517 = C_1$$

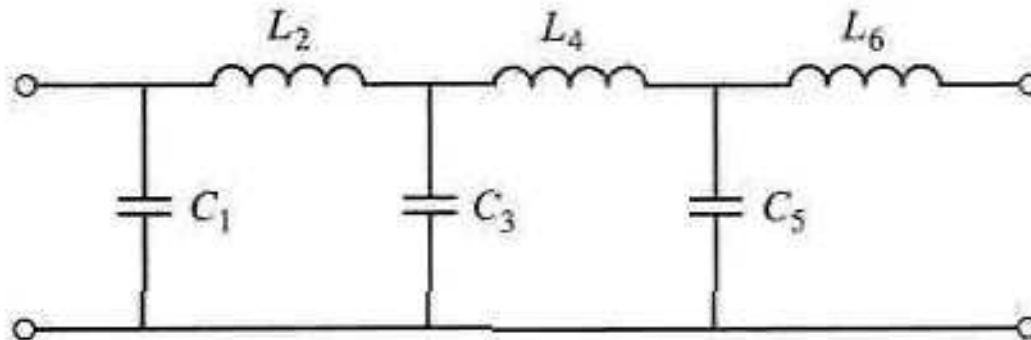
$$g_2 = 1.414 = L_2$$

$$g_3 = 1.932 = C_3$$

$$g_4 = 1.932 = L_4$$

$$g_5 = 1.414 = C_5$$

$$g_6 = 0.517 = L_6$$



# Solutia - 2

$$\beta l_1 = g_1 \frac{Z_l}{R_0} = 5.9^\circ$$

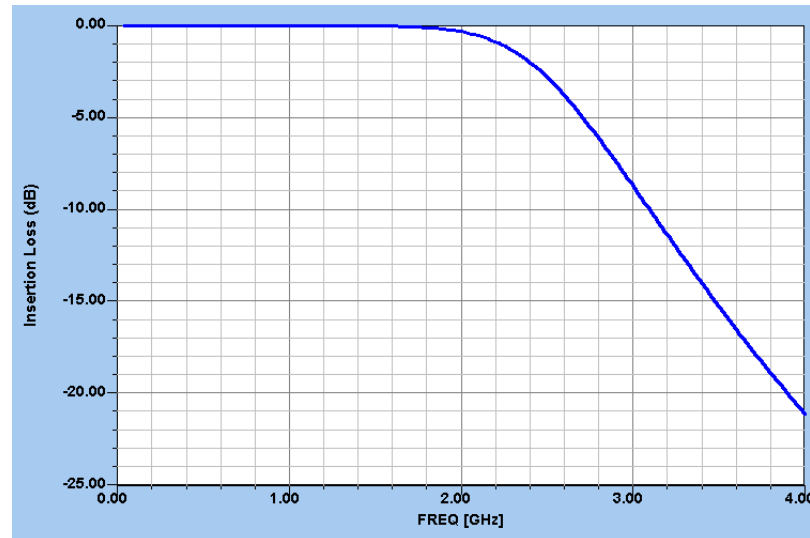
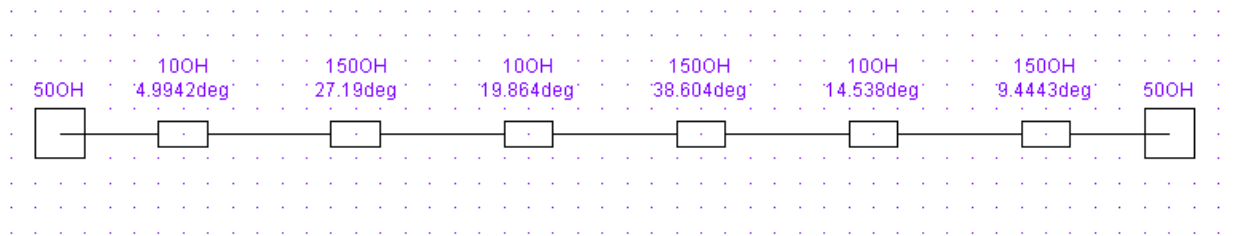
$$\beta l_2 = g_2 \frac{R_0}{Z_h} = 27.0^\circ$$

$$\beta l_3 = g_3 \frac{Z_l}{R_0} = 22.1^\circ$$

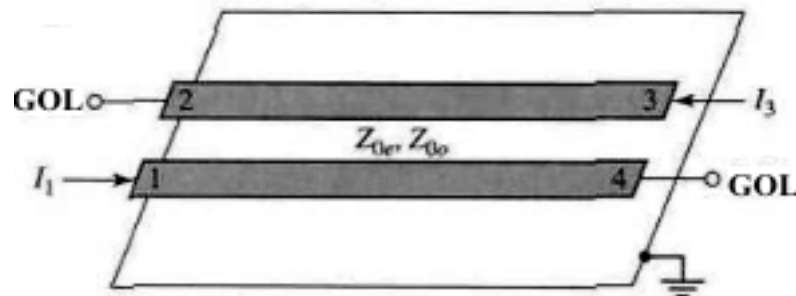
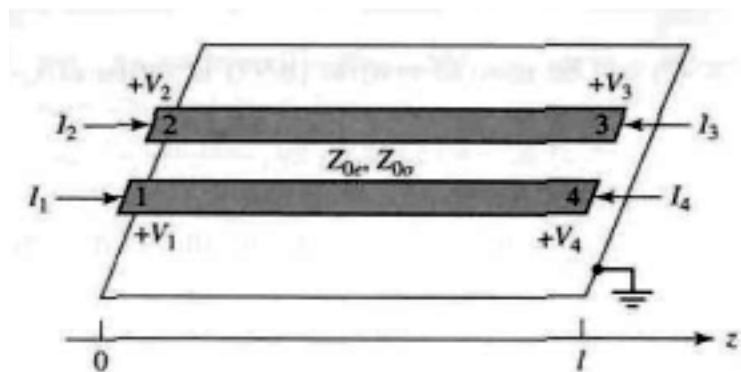
$$\beta l_4 = g_4 \frac{R_0}{Z_h} = 36.9^\circ$$

$$\beta l_5 = g_5 \frac{Z_l}{R_0} = 16.2^\circ$$

$$\beta l_6 = g_6 \frac{R_0}{Z_h} = 9.9^\circ$$



# Proiectarea filtrelor cu linii cuplate

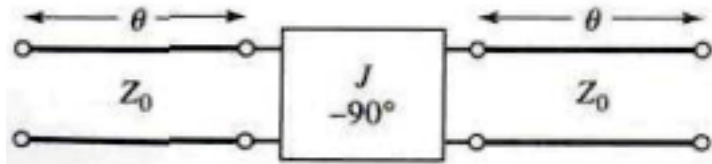


$$V_1 = Z_{11}I_1 + Z_{13}I_3$$

$$V_3 = Z_{31}I_1 + Z_{33}I_3$$

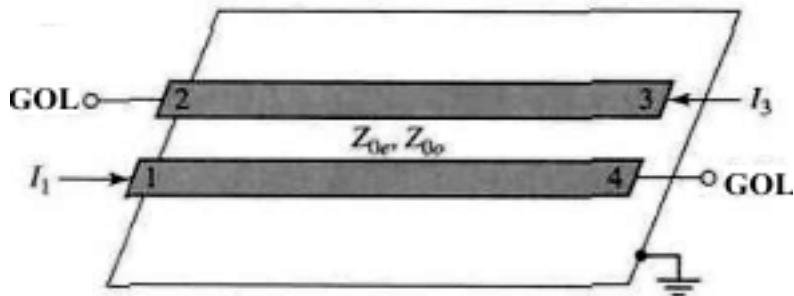
$$Z = \begin{bmatrix} \frac{-j}{2}(Z_{0e} + Z_{0o})\cot\theta & \frac{-j}{2}(Z_{0e} - Z_{0o})\cot\theta & \frac{-j}{2}(Z_{0e} - Z_{0o})\csc\theta & \frac{-j}{2}(Z_{0e} + Z_{0o})\csc\theta \\ \frac{-j}{2}(Z_{0e} - Z_{0o})\cot\theta & \frac{-j}{2}(Z_{0e} + Z_{0o})\cot\theta & \frac{-j}{2}(Z_{0e} + Z_{0o})\csc\theta & \frac{-j}{2}(Z_{0e} - Z_{0o})\csc\theta \\ \frac{-j}{2}(Z_{0e} - Z_{0o})\csc\theta & \frac{-j}{2}(Z_{0e} + Z_{0o})\csc\theta & \frac{-j}{2}(Z_{0e} + Z_{0o})\cot\theta & \frac{-j}{2}(Z_{0e} - Z_{0o})\cot\theta \\ \frac{-j}{2}(Z_{0e} + Z_{0o})\csc\theta & \frac{-j}{2}(Z_{0e} - Z_{0o})\csc\theta & \frac{-j}{2}(Z_{0e} - Z_{0o})\cot\theta & \frac{-j}{2}(Z_{0e} + Z_{0o})\cot\theta \end{bmatrix}$$

# Proiectarea unui filtru trece-bandă cu linii cuplate



$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} \cos \theta & jZ_0 \sin \theta \\ \frac{j \sin \theta}{Z_0} & \cos \theta \end{bmatrix} \cdot \begin{bmatrix} 0 & -j/J \\ -jJ & 0 \end{bmatrix} \cdot \begin{bmatrix} \cos \theta & jZ_0 \sin \theta \\ \frac{j \sin \theta}{Z_0} & \cos \theta \end{bmatrix} =$$

$$\begin{bmatrix} \left( JZ_0 + \frac{1}{JZ_0} \right) \sin \theta \cos \theta & j \left( JZ_0^2 \sin^2 \theta - \frac{\cos^2 \theta}{J} \right) \\ j \left( \frac{1}{JZ_0^2} \sin^2 \theta - J \cos^2 \theta \right) & \left( JZ_0 + \frac{1}{JZ_0} \right) \sin \theta \cos \theta \end{bmatrix}$$



$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} \frac{Z_{11}}{Z_{21}} & \frac{|Z|}{Z_{21}} \\ \frac{1}{Z_{21}} & \frac{Z_{22}}{Z_{21}} \end{bmatrix}$$

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} \frac{Z_{0e} + Z_{0o}}{Z_{0e} - Z_{0o}} \cos \theta & \frac{-j}{2} \left( \frac{(Z_{0e} + Z_{0o})^2}{Z_{0e} - Z_{0o}} \cos^2 \theta + (Z_{0e} - Z_{0o}) \frac{1}{\sin \theta} \right) \\ 2j \frac{1}{Z_{0e} - Z_{0o}} \sin \theta & \frac{Z_{0e} + Z_{0o}}{Z_{0e} - Z_{0o}} \cos \theta \end{bmatrix}$$

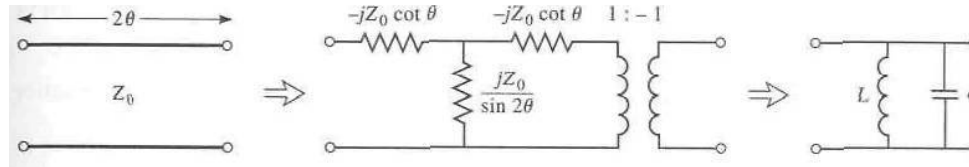
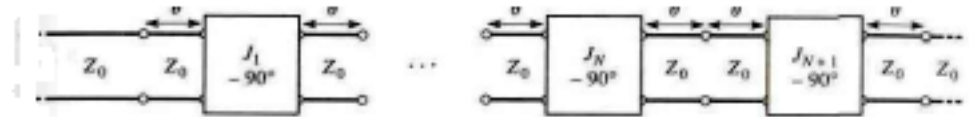
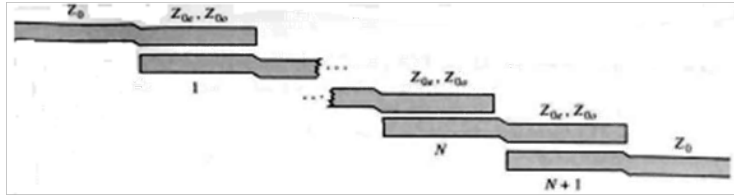
$$\frac{1}{2}(Z_{0e} - Z_{0o}) = JZ_0^2$$

$$Z_{0e} = Z_0 \left[ 1 + JZ_0 + (JZ_0)^2 \right]$$

$$\frac{Z_{0e} + Z_{0o}}{Z_{0e} - Z_{0o}} = JZ_0 + \frac{1}{JZ_0}$$

$$Z_{0o} = Z_0 \left[ 1 - JZ_0 + (JZ_0)^2 \right]$$

# Calculul sectiunilor interne



$$2\theta = \beta l = \omega l / v_p = (\omega_0 + \Delta\omega)\pi / \omega_0 = \pi(1 + \Delta\omega / \omega_0)$$

$$\theta \approx \pi/2 \quad Z_{12} = \frac{jZ_0}{\sin \pi(1 + \Delta\omega / \omega_0)} \approx \frac{-jZ_0\omega_0}{\pi(\omega - \omega_0)}$$

$$Z = \frac{-jL\omega_0^2}{2(\omega - \omega_0)}$$

$$L = \frac{2Z_0}{\pi\omega_0} \quad C = \frac{1}{\omega_0^2 L} = \frac{\pi}{2Z_0\omega_0}$$

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} \frac{Z_{11}}{Z_{12}} & \frac{Z_{11}^2 - Z_{12}^2}{Z_{12}} \\ 1 & \frac{Z_{11}}{Z_{12}} \end{bmatrix} \cdot \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} \frac{-Z_{11}}{Z_{12}} & \frac{Z_{12}^2 - Z_{11}^2}{Z_{12}} \\ \frac{-1}{Z_{12}} & \frac{-Z_{11}}{Z_{12}} \end{bmatrix}$$

$$Z_{12} = \frac{-1}{C} = \frac{jZ_0}{\sin 2\theta}$$

$$Z_{11} = Z_{22} = -Z_{12}A = -jZ_0 \cot 2\theta$$

$$Z_{11} - Z_{12} = -jZ_0 \frac{1 + \cos 2\theta}{\sin 2\theta} = -jZ_0 \cot \theta$$



# Calculul sectiunilor de capat



$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} 0 & -j/J \\ -jJ & 0 \end{bmatrix}$$

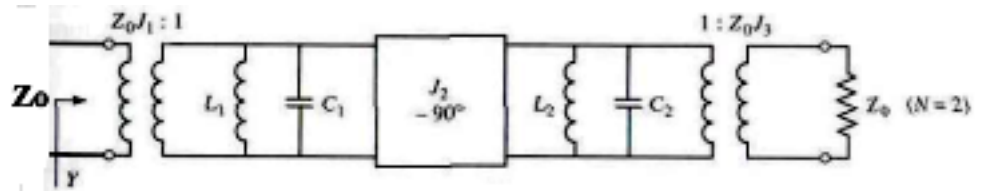
$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} \frac{1}{N} & 0 \\ 0 & N \end{bmatrix} \cdot \begin{bmatrix} 0 & -jZ_0 \\ \frac{-j}{Z_0} & 0 \end{bmatrix} = \begin{bmatrix} 0 & \frac{-jZ_0}{N} \\ \frac{-jN}{Z_0} & 0 \end{bmatrix}$$

$$N = JZ_0$$

# Circuitul echivalent al filtrului

$$Y = \frac{1}{J_1^2 Z_0^2} \left\{ j\omega C_1 + \frac{1}{j\omega L_1} + \frac{J_2^2}{j\sqrt{C_2/L_2}[(\omega/\omega_0) - (\omega_0/\omega)] + Z_0 J_3^2} \right\} =$$

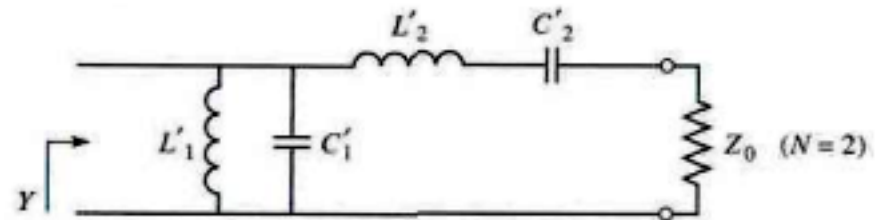
$$= \frac{1}{J_1^2 Z_0^2} \left\{ j\sqrt{\frac{C_1}{L_1}} \left( \frac{\omega}{\omega_0} - \frac{\omega_0}{\omega} \right) + \frac{J_2^2}{j\sqrt{C_2/L_2}[(\omega/\omega_0) - (\omega_0/\omega)] + Z_0 J_3^2} \right\}$$



$$j\omega C_2 + \frac{1}{j\omega L_2} + Z_0 J_3^2 = j\sqrt{\frac{C_2}{L_2}} \left( \frac{\omega}{\omega_0} - \frac{\omega_0}{\omega} \right) + Z_0 J_3^2$$

$$Y = j\omega C'_1 + \frac{1}{j\omega L'_1} + \frac{1}{j\omega L'_2 + (1/j\omega C'_2) + Z_0} =$$

$$= j\sqrt{\frac{C'_1}{L'_1}} \left( \frac{\omega}{\omega_0} - \frac{\omega_0}{\omega} \right) + \frac{1}{j\sqrt{L'_2/C'_2}[(\omega/\omega_0) - (\omega_0/\omega)] + Z_0}$$



$$\frac{1}{J_1^2 Z_0^2} \sqrt{\frac{C_1}{L_1}} = \sqrt{\frac{C'_1}{L'_1}}$$

$$\frac{J_1^2 Z_0^2}{J_2^2} \sqrt{\frac{C_2}{L_2}} = \sqrt{\frac{L'_2}{C'_2}}$$

$$\frac{J_1^2 Z_0^3 J_3^2}{J_2^2} = Z_0$$

# Relatiile de calcul ale filtrului

$$L'_1 = \frac{\Delta Z_0}{\omega_0 g_1}$$

$$C'_1 = \frac{g_1}{\Delta \omega_0 Z_0}$$

$$L'_2 = \frac{g_2 Z_0}{\Delta \omega_0}$$

$$C'_2 = \frac{\Delta}{\omega_0 g_2 Z_0}$$

$$L_n = \frac{2Z_0}{\pi \omega_0}$$

$$C_n = \frac{1}{\omega_0^2 L_n} = \frac{\pi}{2Z_0 \omega_0}$$

$$J_1 Z_0 = \left( \frac{C_1 L'_1}{L_1 C'_1} \right)^{1/4} = \sqrt{\frac{\pi \Delta}{2g_1}}$$

$$J_2 Z_0 = J_1 Z_0^2 \left( \frac{C_2 C'_2}{L_2 L'_2} \right)^{1/4} = \frac{\pi \Delta}{2\sqrt{g_1 g_2}}$$

$$J_3 Z_0 = \frac{J_2}{J_1} = \sqrt{\frac{\pi \Delta}{2g_2}}$$

$$\Delta = (\omega_2 - \omega_1) / \omega_0$$

$$Z_0 J_1 = \sqrt{\frac{\pi \Delta}{2g_1}}$$

$$Z_0 J_n = \frac{\pi \Delta}{2\sqrt{g_{n-1} g_n}} \quad n = 2, 3, \dots, N$$

$$Z_0 J_{N+1} = \sqrt{\frac{\pi \Delta}{2g_N g_{N+1}}}$$

$$(Z_{0e})_k = Z_0 \left[ 1 + J_k Z_0 + (J_k Z_0)^2 \right]$$

$$(Z_{0o})_k = Z_0 \left[ 1 - J_k Z_0 + (J_k Z_0)^2 \right]$$

# Exemplu

Proiectați un filtru trece-bandă cu  $N=3$  și ripluri de 0.5 dB în bandă. Frecvența centrală este de 2 GHz, banda de 10% și

$$Z_0 = 50\Omega$$

. Care este atenuarea la 1.8 GHz ?

# Solutie

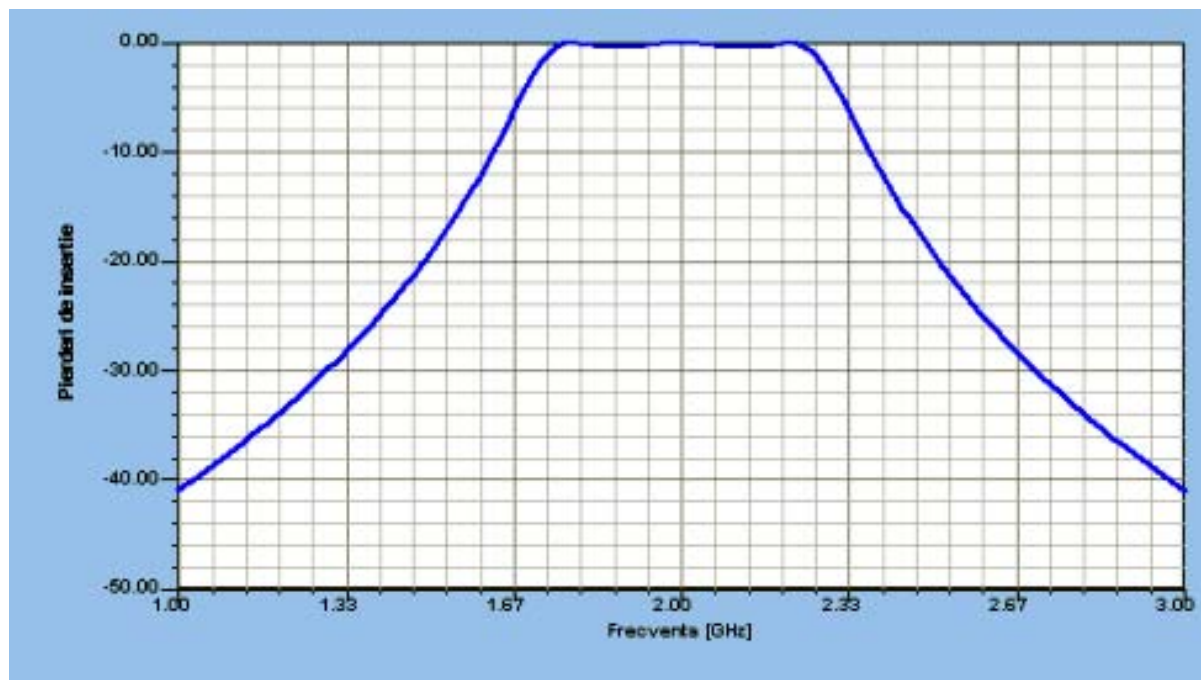
$$\omega \leftarrow \frac{1}{\Delta} \left( \frac{\omega}{\omega_0} - \frac{\omega_0}{\omega} \right) = \frac{1}{0.1} \left( \frac{1.8}{2.0} - \frac{2.0}{1.8} \right) = -2.11$$

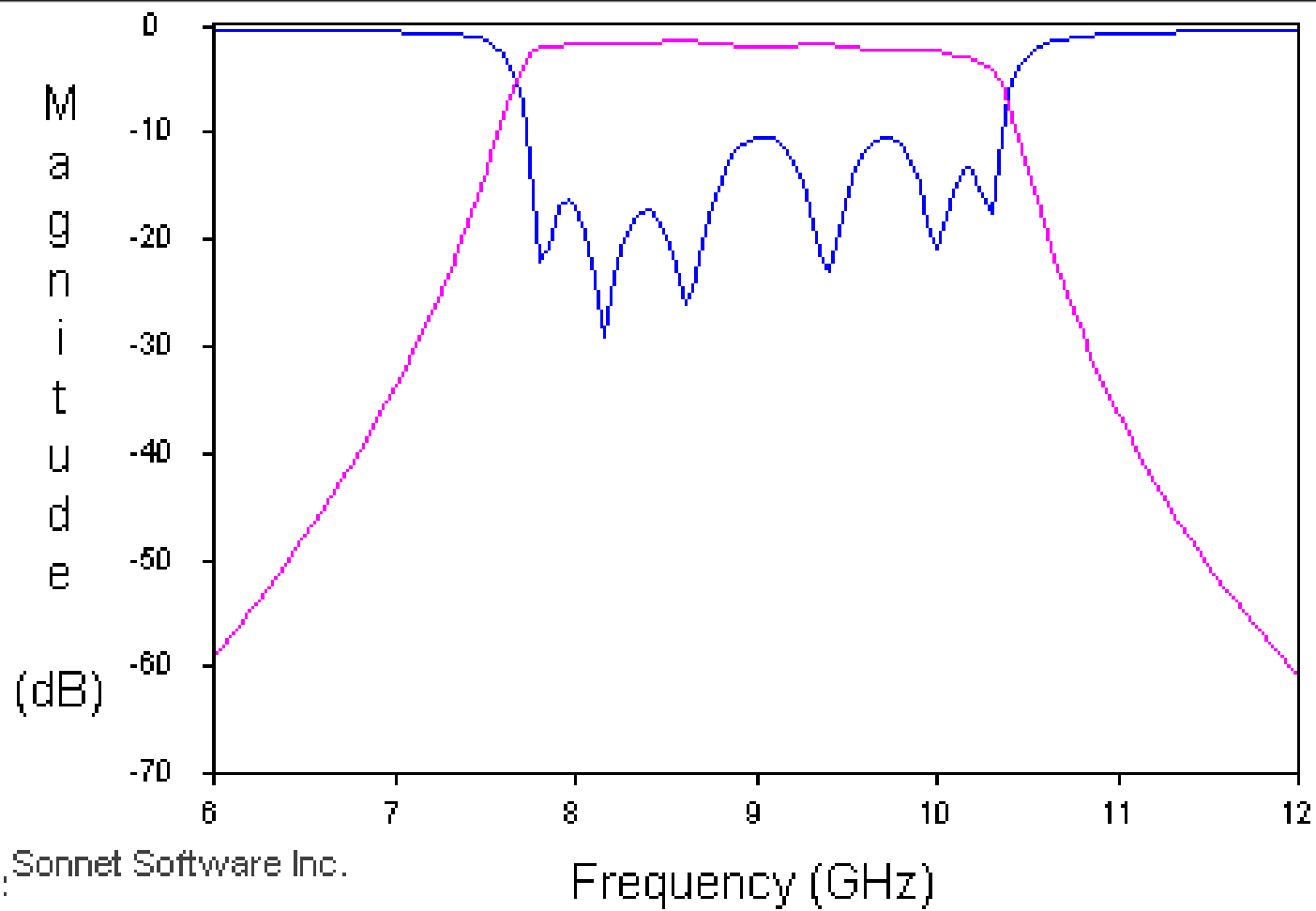
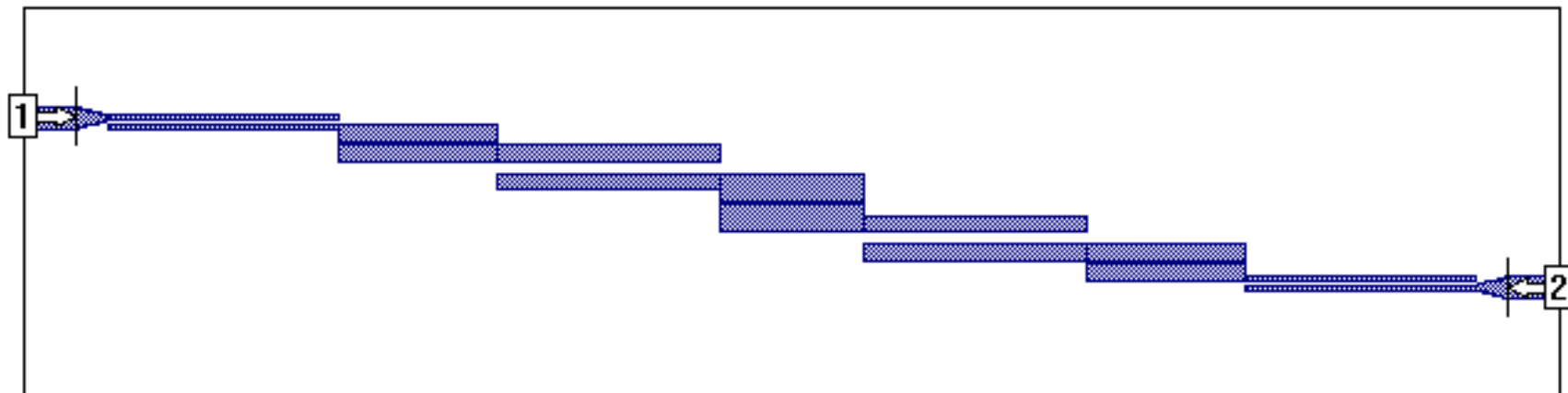
$$L_A \text{ (dB)} = 10 \log \left[ 1 + \varepsilon_r \left( \text{ch}^2 n \left( \text{arcch} \left( \frac{\omega'_s}{\omega'_l} \right) \right) \right) \right] =$$

$$10 \log \left[ 1 + 0.122 \left( \text{ch}^2 3 (\text{arcch}(2.11)) \right) \right] = 20.8 \text{ dB}$$

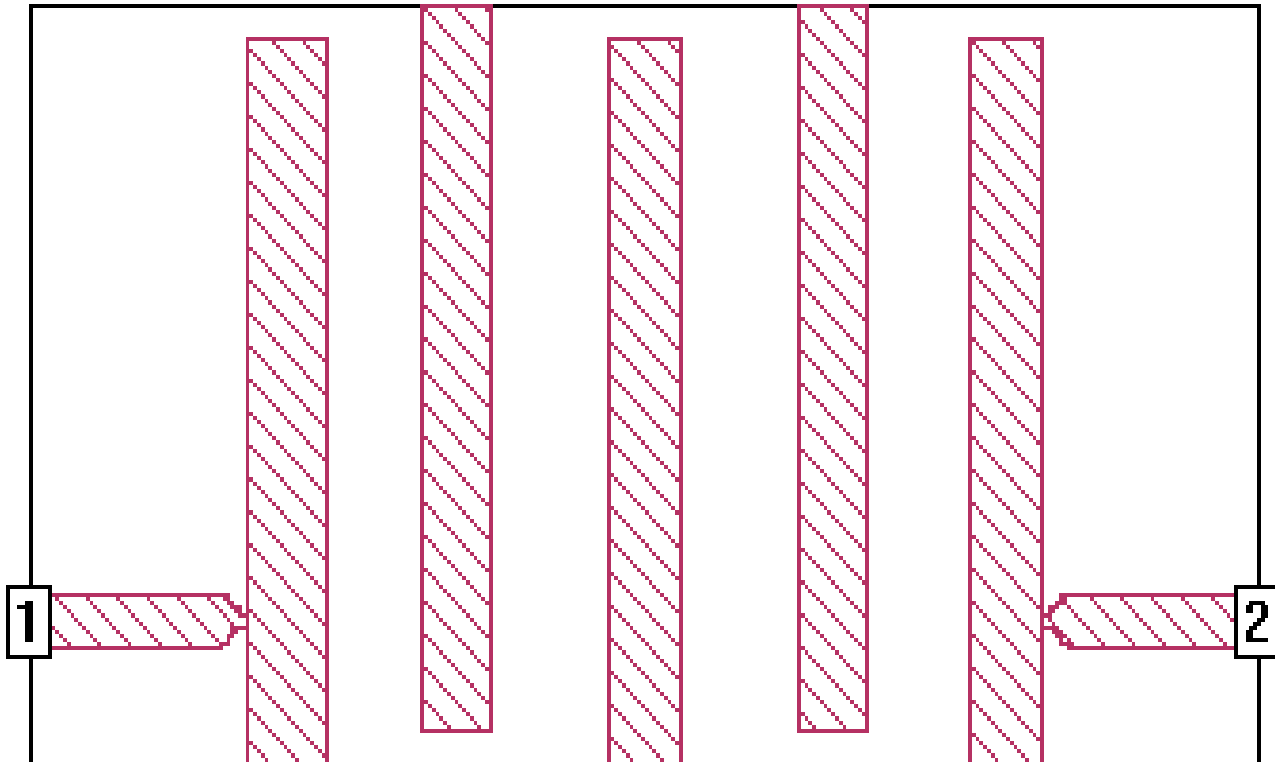
n	$g_n$	$Z_0 J_n$	$Z_{0e}(\Omega)$	$Z_{0o}(\Omega)$
1	1.5963	0.3137	70.61	39.24
2	1.0967	0.1187	56.64	44.77
3	1.5963	0.1187	56.64	44.77
4	1.0000	0.3137	70.61	39.24

# Rezultatul simulării



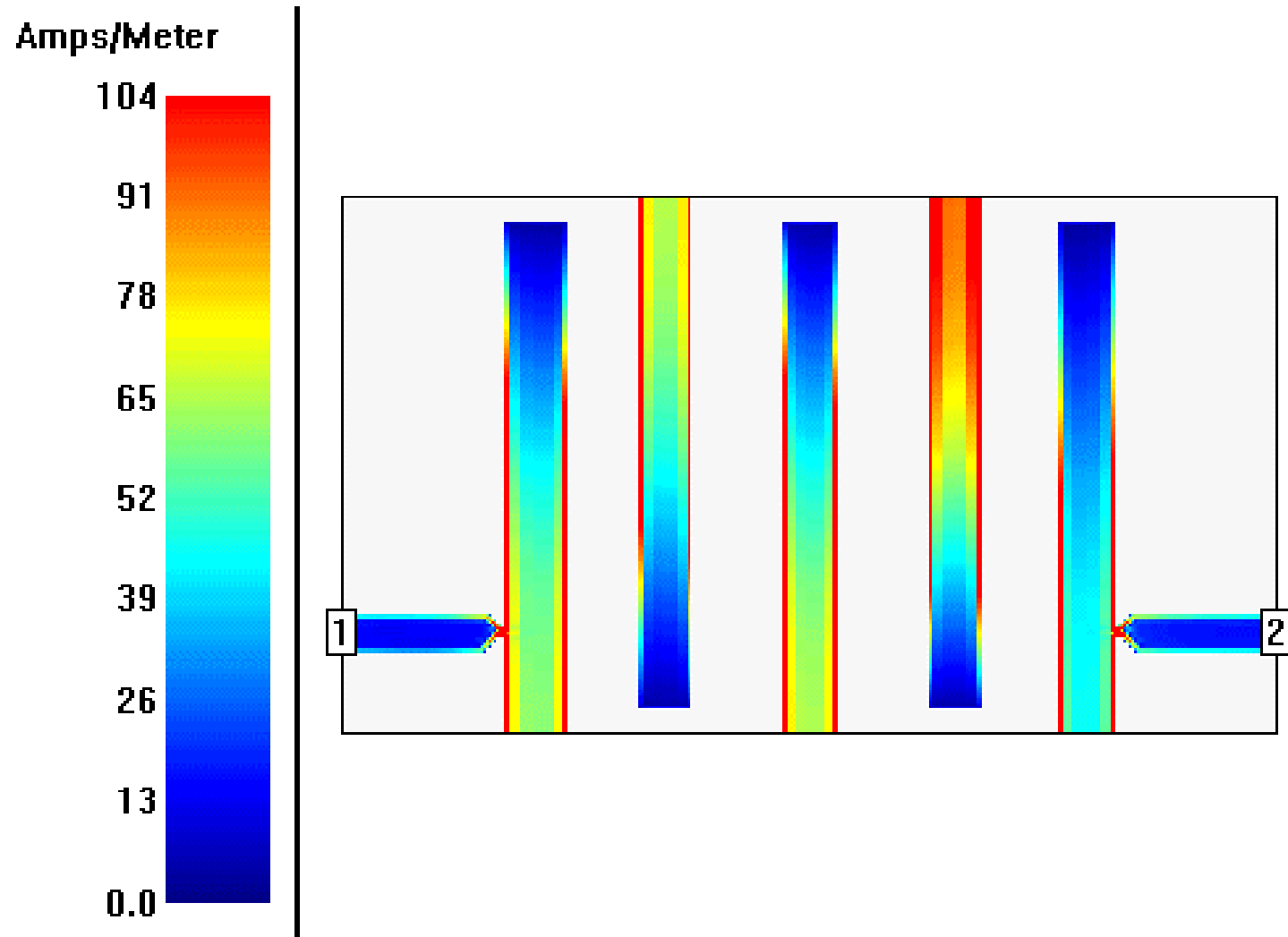


# Filtru trece banda interdigital

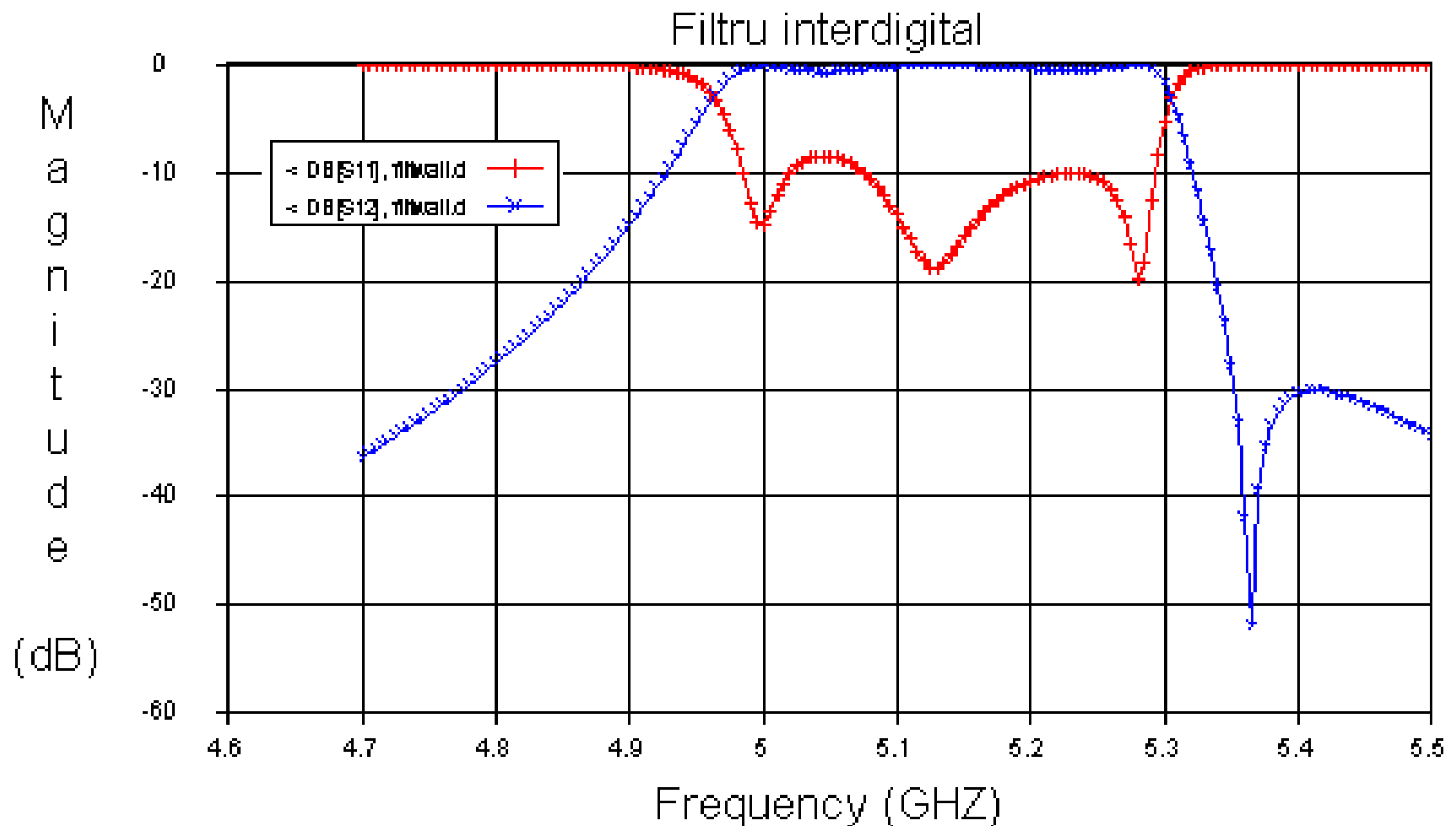




# Filtru trece banda interdigital



# Filtru trece banda interdigital



# Filtru hairpin

